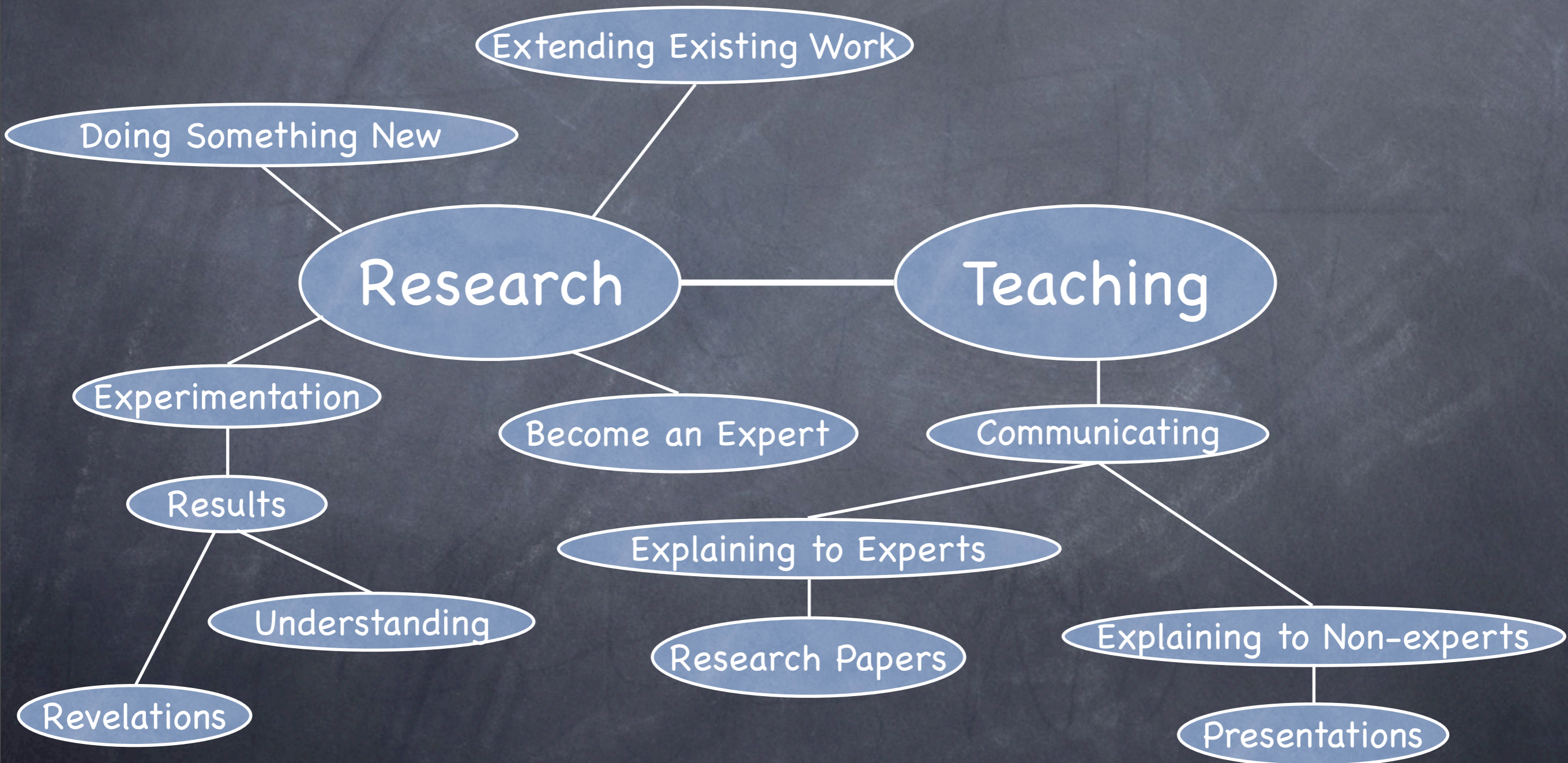


Reasoning About Programs

Mark Wheelhouse

PhD Student
Department of Computing
Imperial College London

So What is a PhD Anyway?



What am I Doing?

“Context Logic, Tree Update and Concurrency”

What am I Doing?

"Context Logic, Tree Update and Concurrency"

Huh?!

What am I Doing?

"Context Logic, Tree Update, and Concurrency"

Huh?!
What's He Talking About?!

What am I Doing?

"Context Logic, Tree Update, and Concurrency"

Huh?!
What's He Talking About?!

Using Mathematics to prove properties about computer programs

Sometimes we want to be 100% sure the computer is doing what it should be

Why Prove Programs? A History Lesson

Why Prove Programs? A History Lesson

1980's - Therac 25

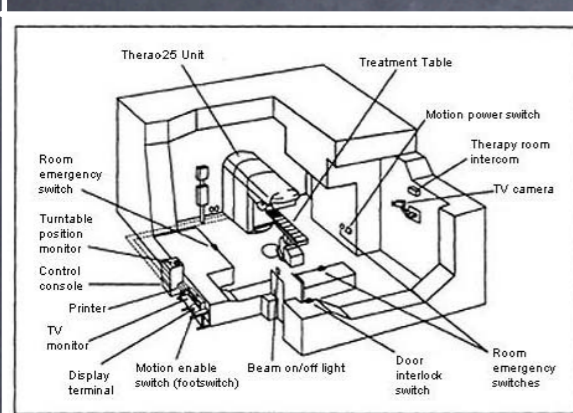


Figure 1. Typical Therac-25 facility

Why Prove Programs? A History Lesson

1980's - Therac 25

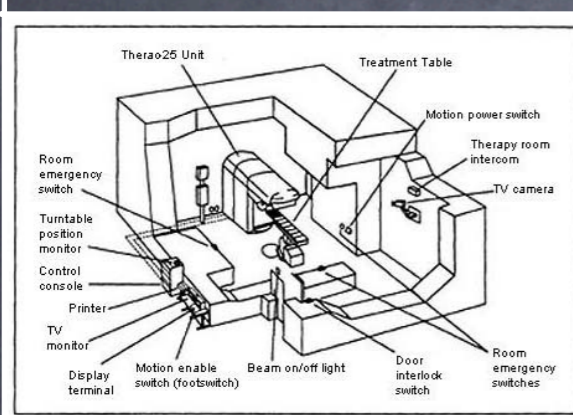


Figure 1. Typical Therac-25 facility

race
condition

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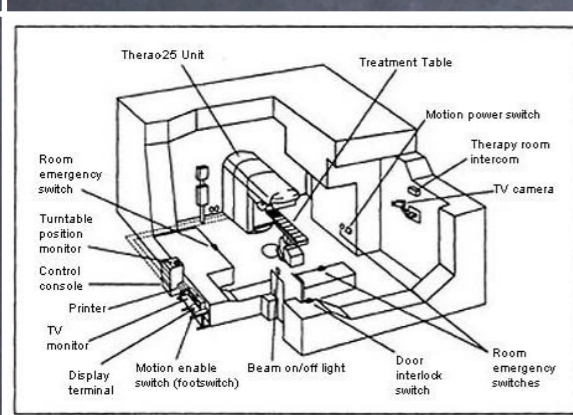
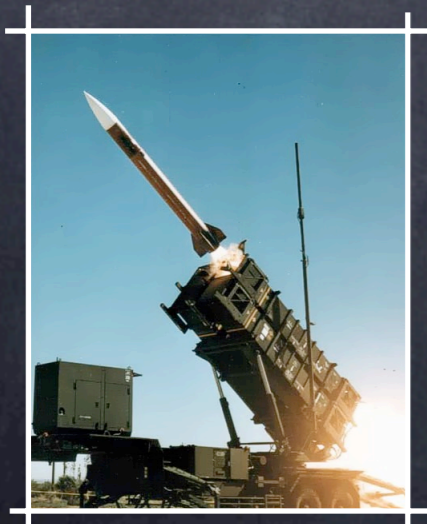


Figure 1. Typical Therac-25 facility

race
condition

1991 - MIM-104 Patriot



Why Prove Programs? A History Lesson

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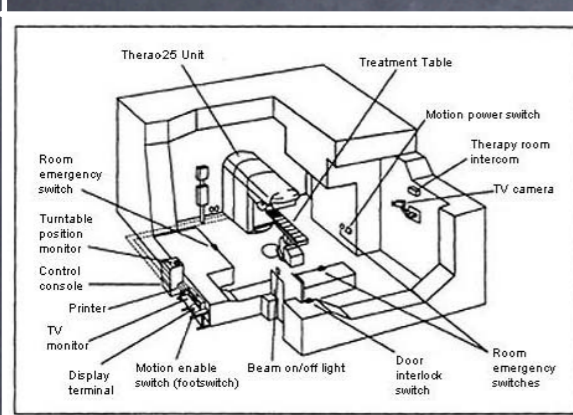
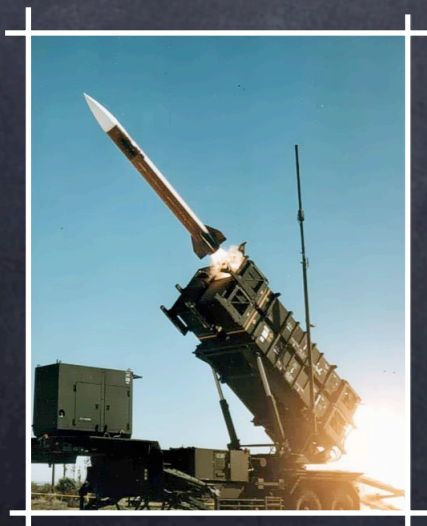


Figure 1. Typical Therac-25 facility

race
condition

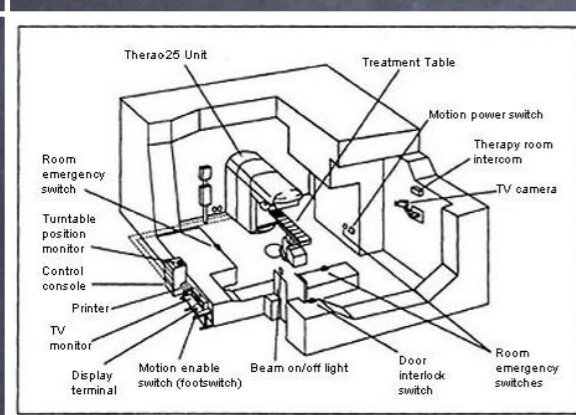
1991 - MIM-104 Patriot



rounding
error

Why Prove Programs? A History Lesson

1980's - Therac 25

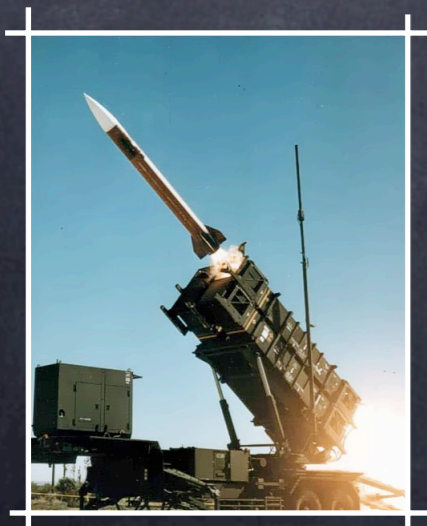


race
condition

1996 - Ariane 5



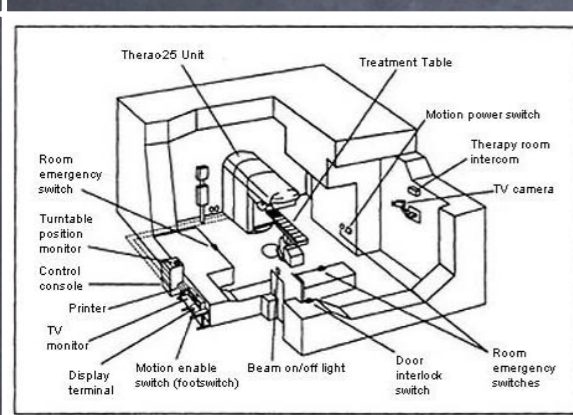
1991 - MIM-104 Patriot



rounding
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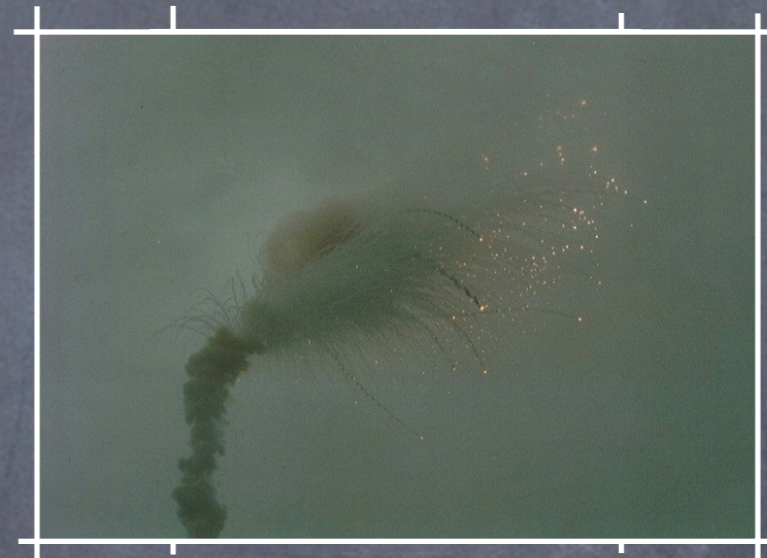
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1980's - Therac 25



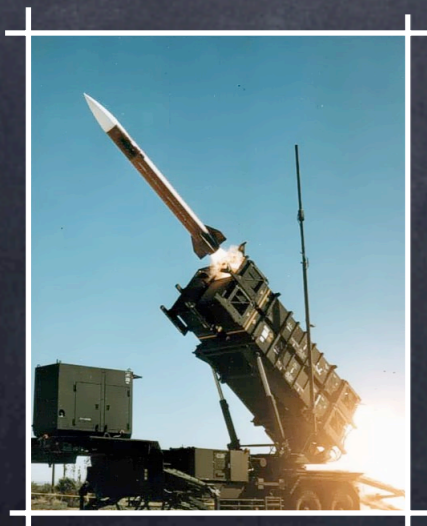
race
condition

1996 - Ariane 5



data
overflow!

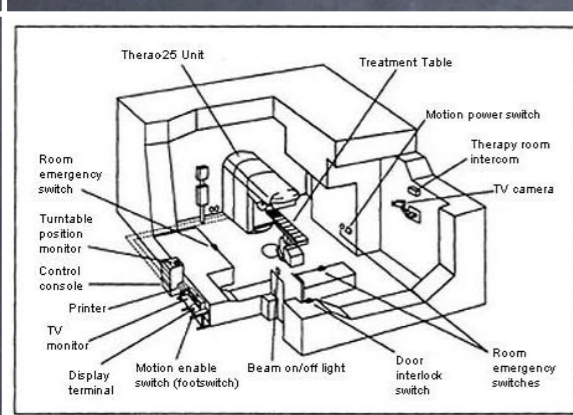
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rounding
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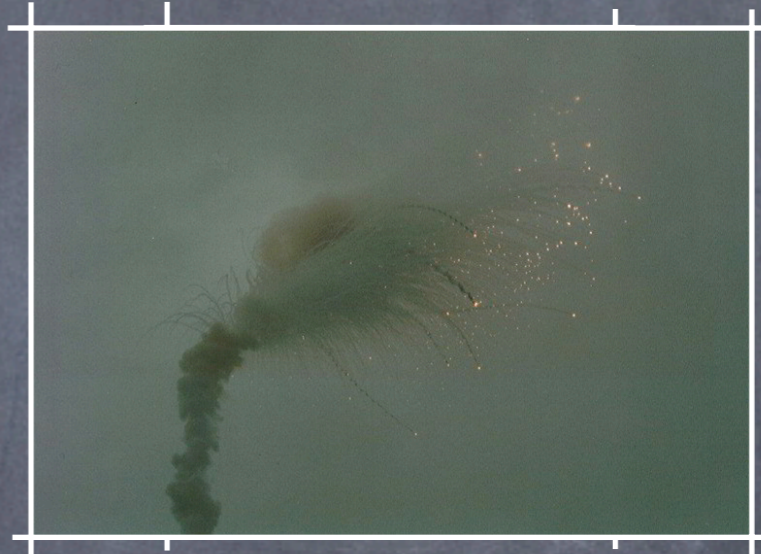
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1980's - Therac 25



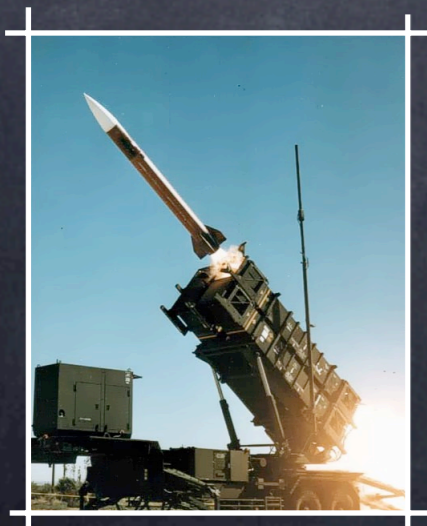
race
condition

1996 - Ariane 5



data
overflow!

1991 - MIM-104 Patriot



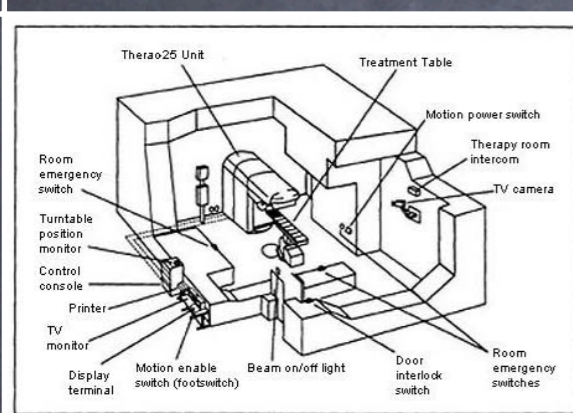
rounding
error

1997 - USS Yorktown



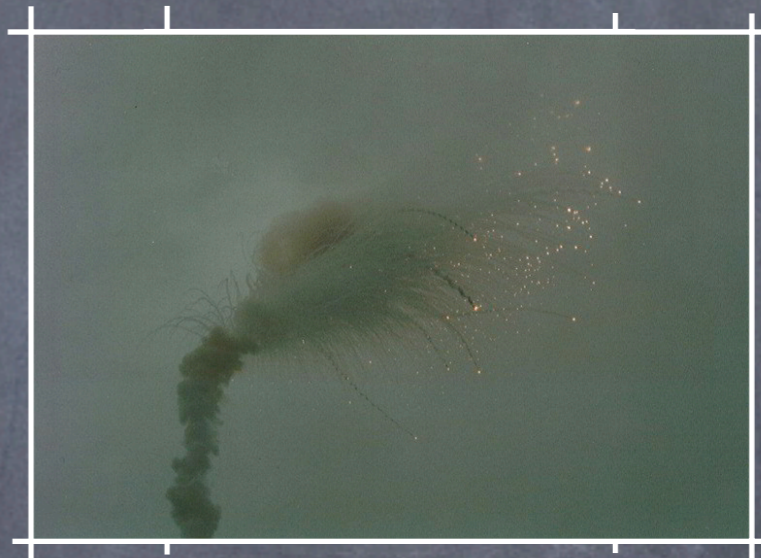
Why Prove Programs? A History Lesson

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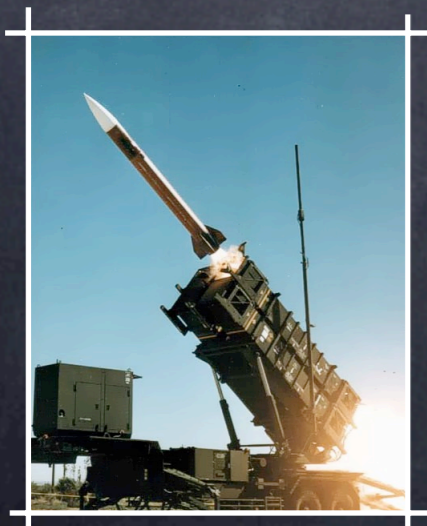
race
condition

1996 - Ariane 5



data
overflow!

1991 - MIM-104 Patriot



rounding
error

1997 - USS Yorktown



divide by
zero error!

What Kind of Systems do
We Want to be Sure of?

What Kind of Systems do We Want to be Sure of?

Internet Banking

Automatic Breaking

Nuclear Power Stations

Flight Control Systems

Building Design Software

Spaceships

IFF Targeting Systems

Heart Monitors

Pacemakers

What Kind of Systems do We Want to be Sure of?

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IFF Targeting Systems

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Pacemakers

i.e. - Anything that is safety critical

- When the cost of system failure is huge

Spotting Failure

- We want to spot when a system can fail.
- We want to prove that a system will not fail.
- We can use mathematics (namely logic) to do this.

Logic – The Basics

boolean variables – “have one of two values”

$p =$	true	false
	1	0

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boolean operators – “ways of combining variables”

and: \wedge

or: \vee

implies: \Rightarrow

Logic – The Basics

boolean variables – “have one of two values”

$p =$ **true** **false**
 1 0

boolean operators – “ways of combining variables”

and: \wedge

p	q	$p \wedge q$
0	0	0
0	1	0
1	0	0
1	1	1

or: \vee

p	q	$p \vee q$
0	0	0
0	1	1
1	0	1
1	1	1

implies: \Rightarrow

p	q	$p \Rightarrow q$
0	0	1
0	1	1
1	0	0
1	1	1

Logic – Predicates

X, Y, Z are things (objects, people, concepts,...)

$\text{isRed}(X) = \text{true}$ if X is red

$\text{isRound}(X) = \text{true}$ if X is round

$\text{isRedBall}(X) = \text{true}$ if X is a red ball

Logic – Predicates

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$\text{isRed}(X)$ = true if X is red

$\text{isRound}(X)$ = true if X is round

$\text{isRedBall}(X)$ = true if X is a red ball

$\text{isRedBall}(X) \Rightarrow \text{isRed}(X) \wedge \text{isRound}(X)$

Logic – Structures

another way of looking at this using a satisfaction relation,

\models

$X \models \text{isRed} \iff X \text{ is red}$

$X \models \text{isRound} \iff X \text{ is round}$

$X \models \text{isRedBall} \iff X \text{ is a red ball}$

Logic – Structures

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$\text{isRedBall} \Rightarrow \text{isRed} \wedge \text{isRound}$

Logic – Structures

data \models Tree-Formula

tree $T ::=$

Logic – Structures

data \models Tree-Formula

tree $T ::= 0$ empty tree

Logic – Structures

$\text{data} \models \text{Tree-Formula}$

tree $T ::= 0$ empty tree
 $n[T]$ tree node

Logic – Structures

data \models Tree-Formula

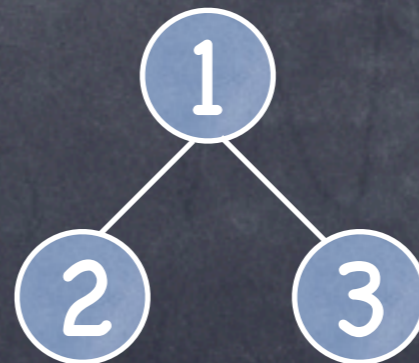
tree $T ::= 0$ empty tree
 $n[T]$ tree node
 $T \mid T$ ordered trees

Logic – Structures

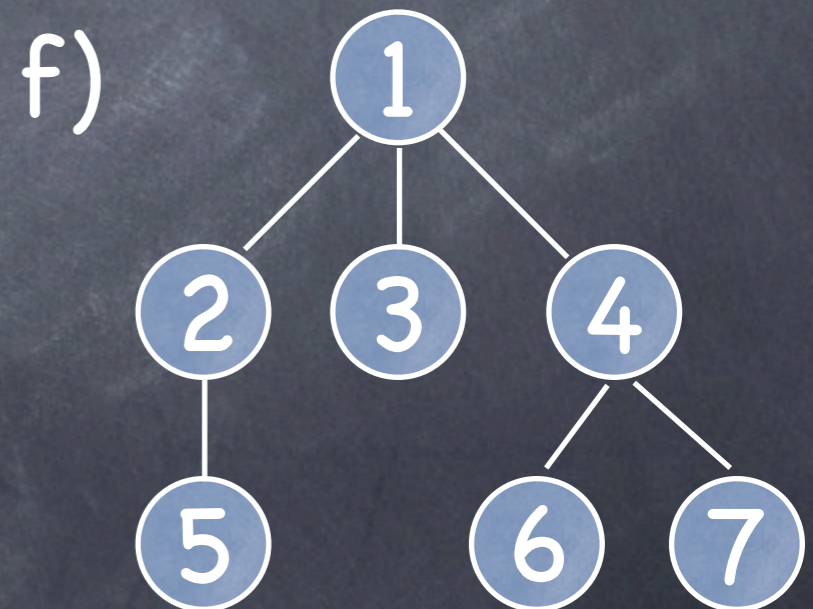
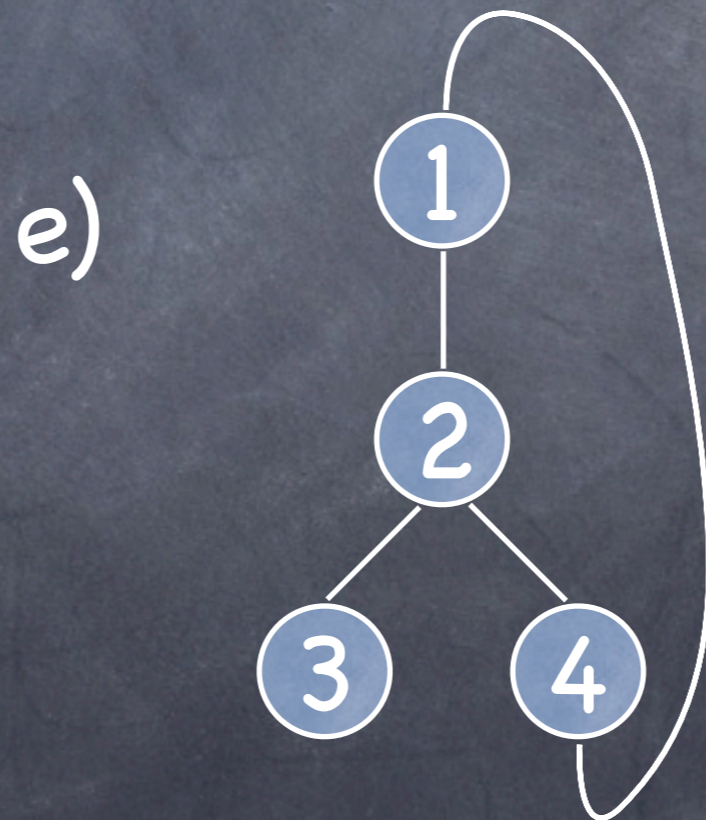
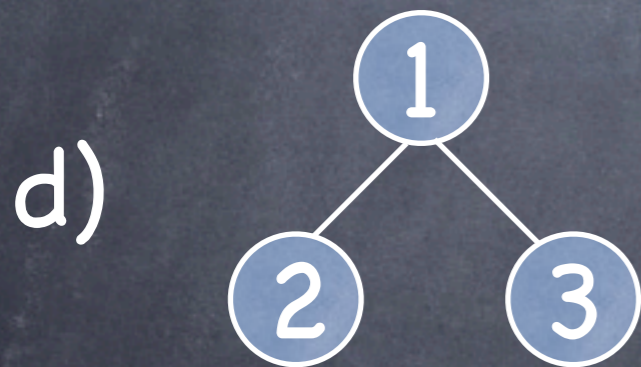
data \models Tree-Formula

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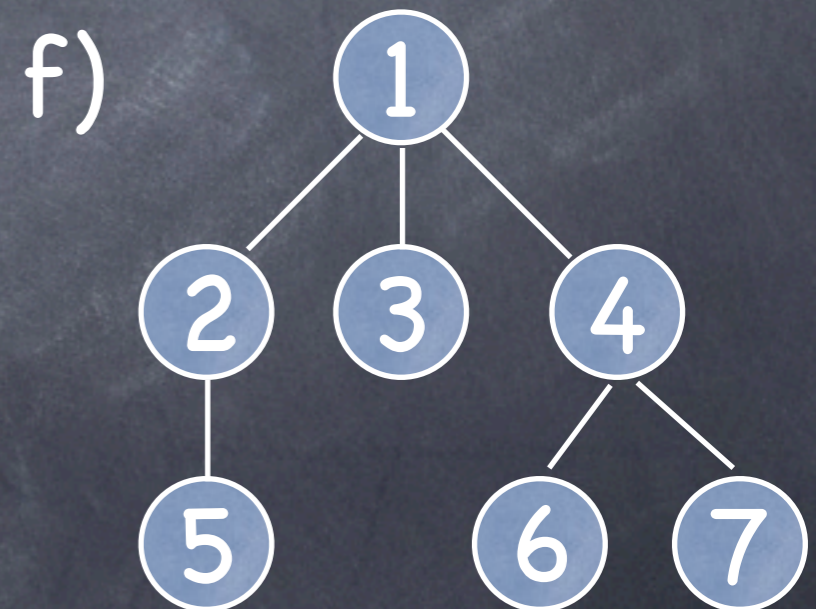
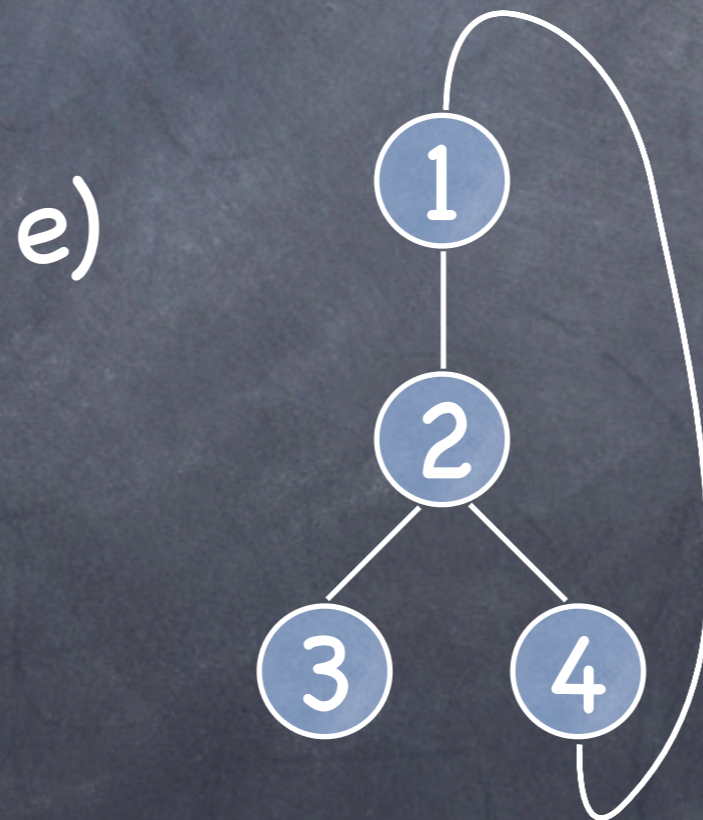
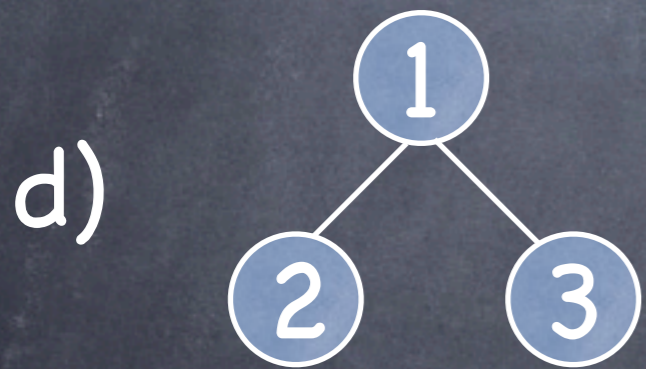
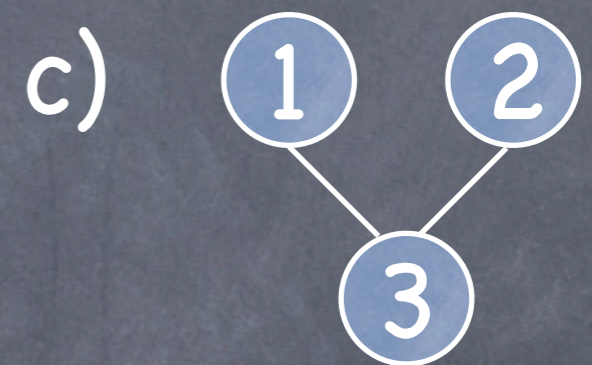
Eg: $1[2[0] \mid 3[0]]$



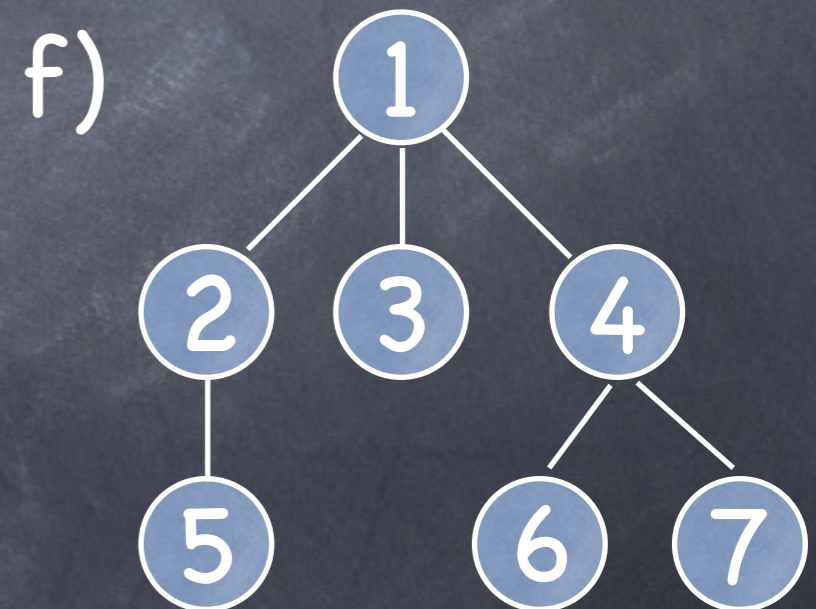
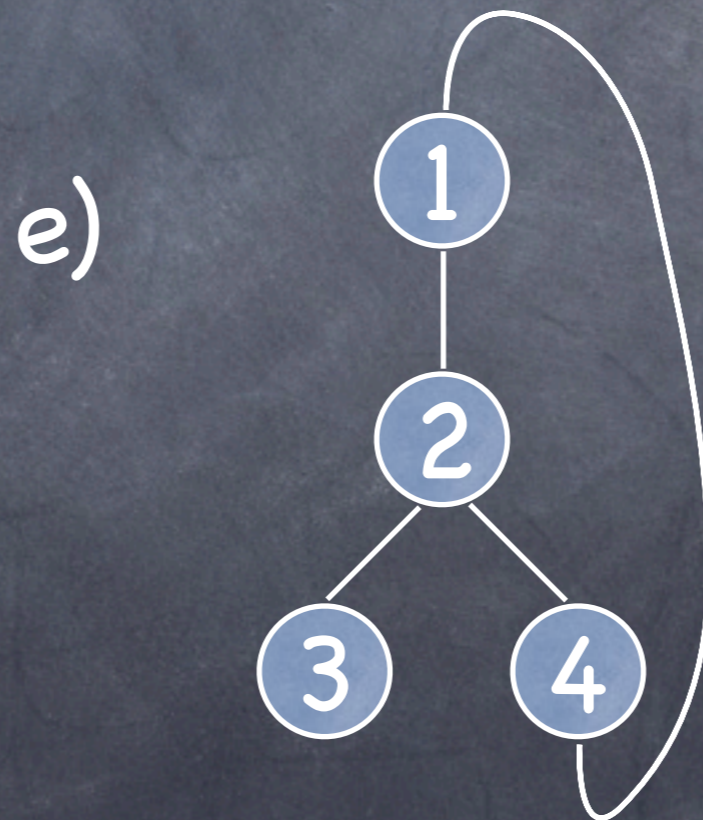
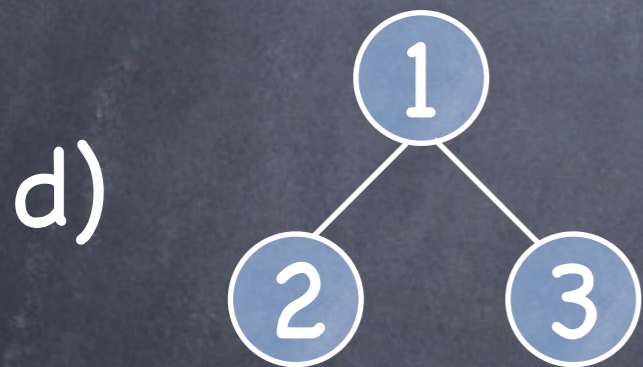
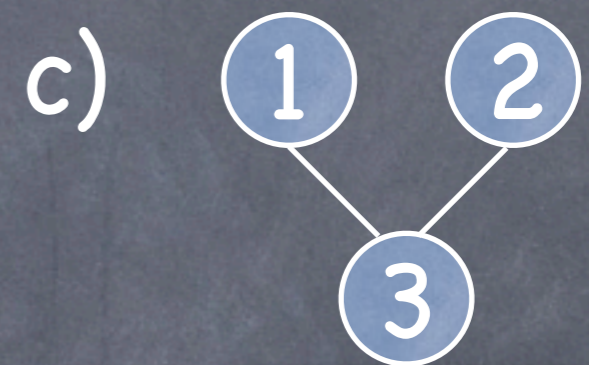
Tree Examples



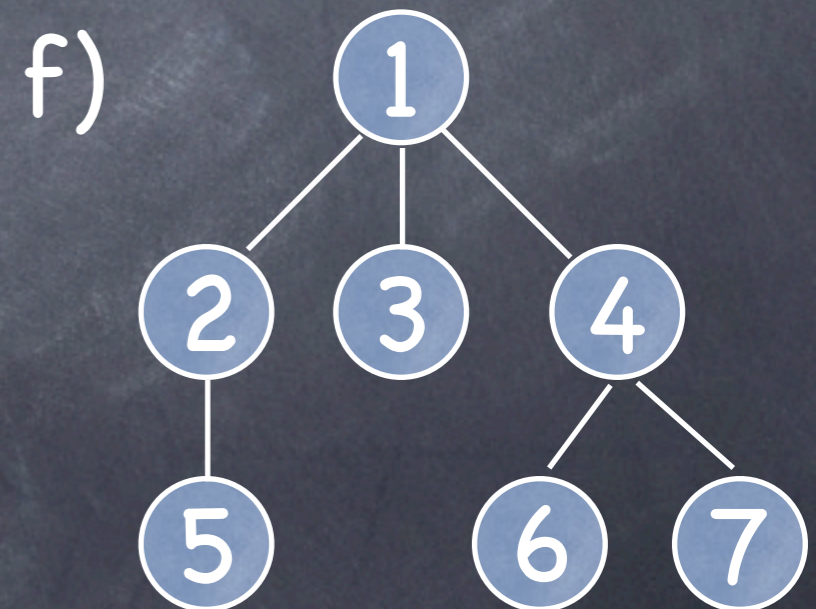
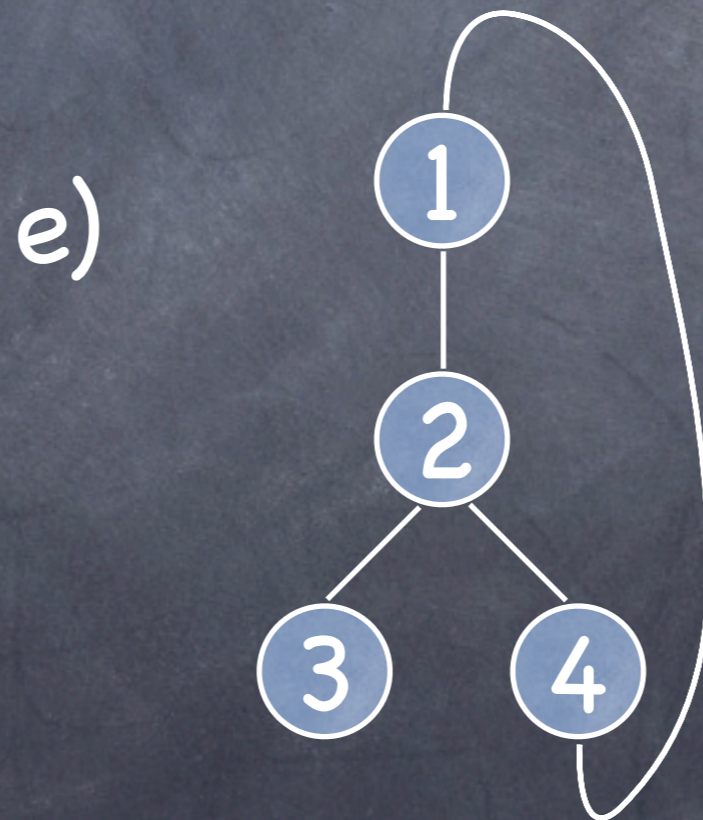
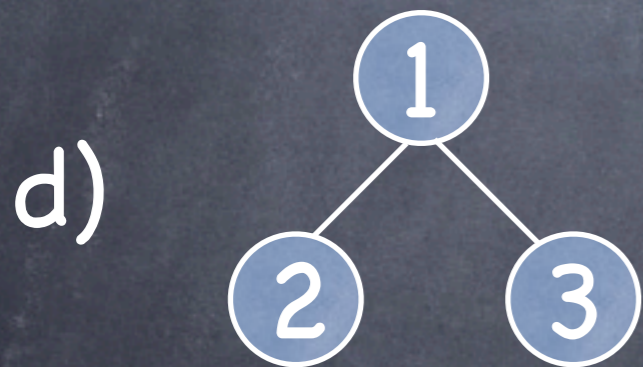
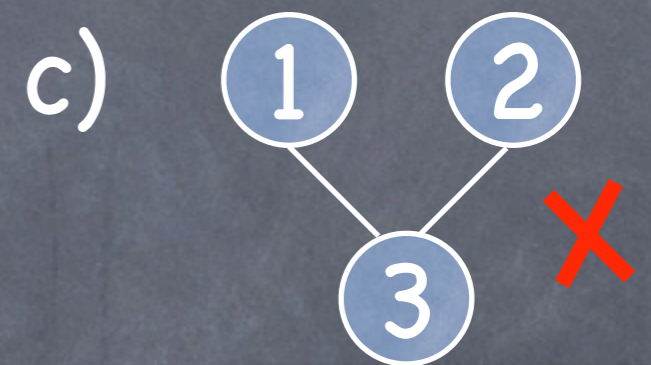
Tree Examples



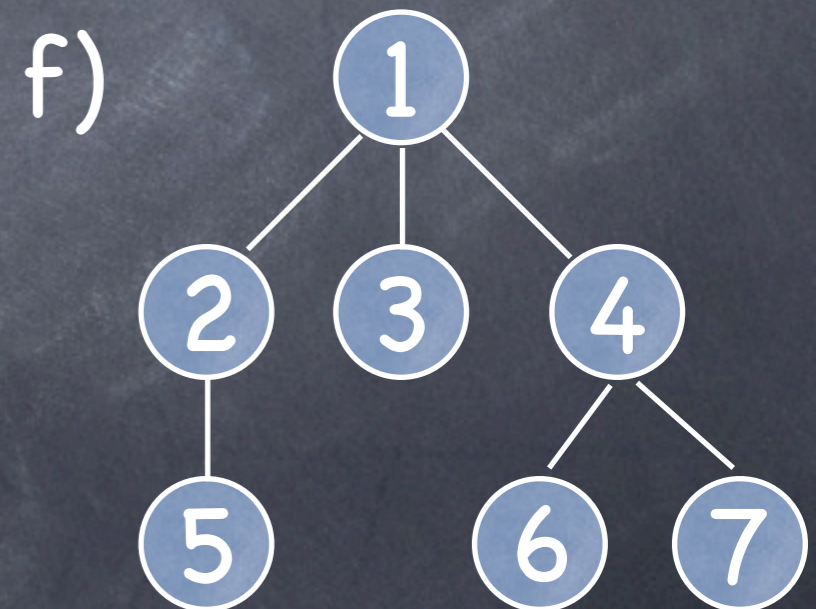
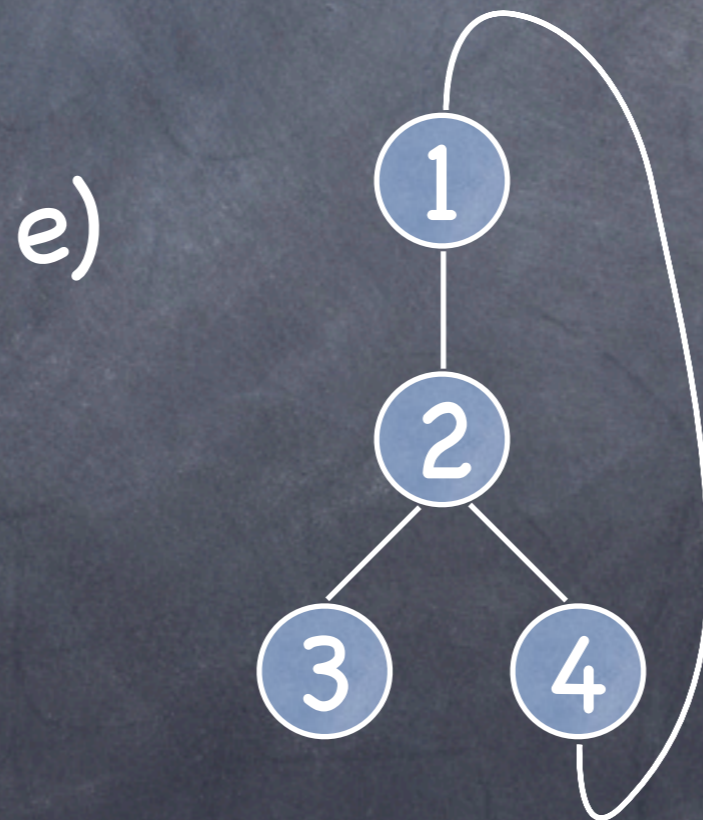
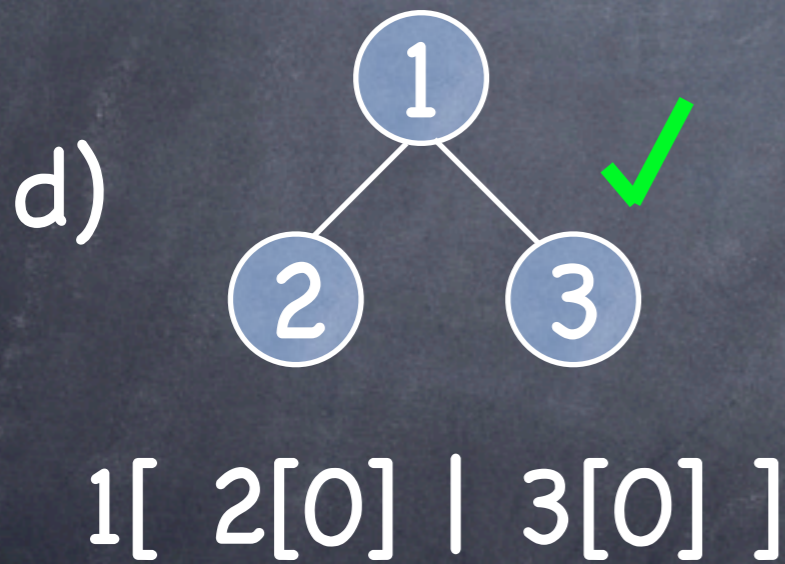
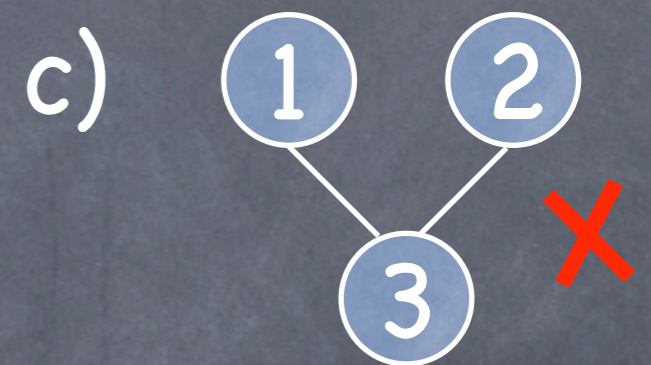
Tree Examples



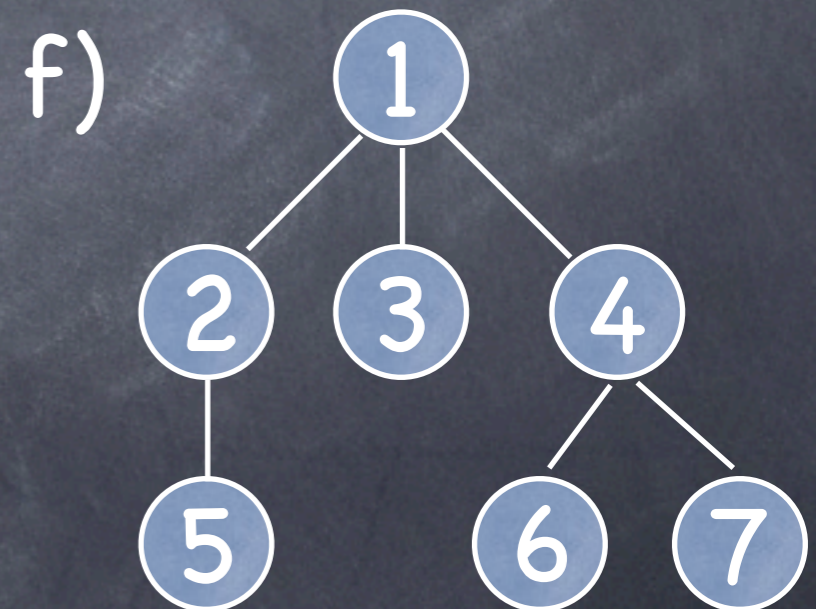
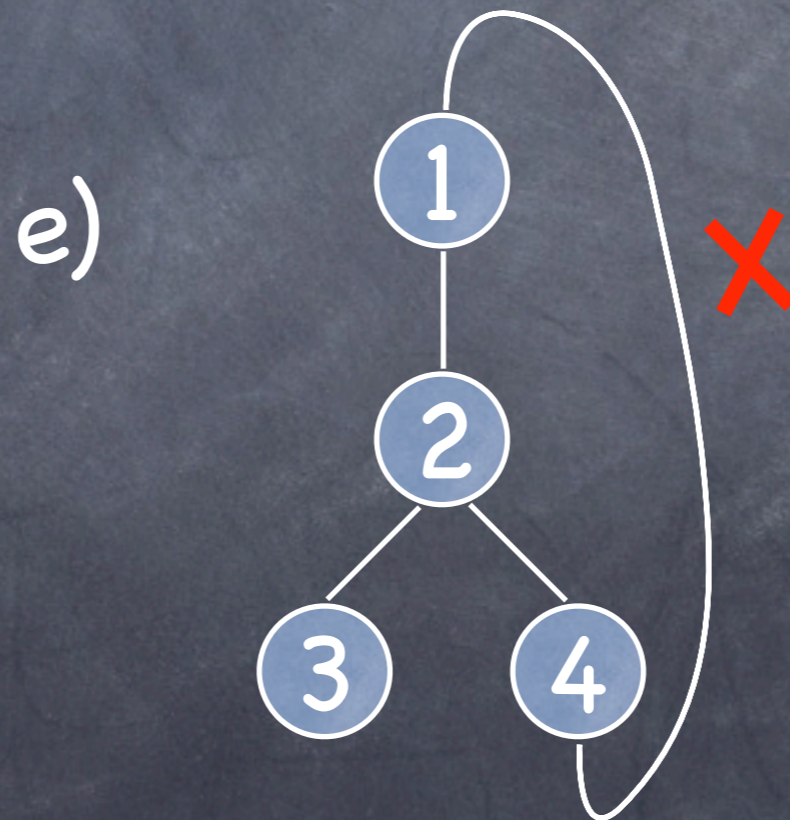
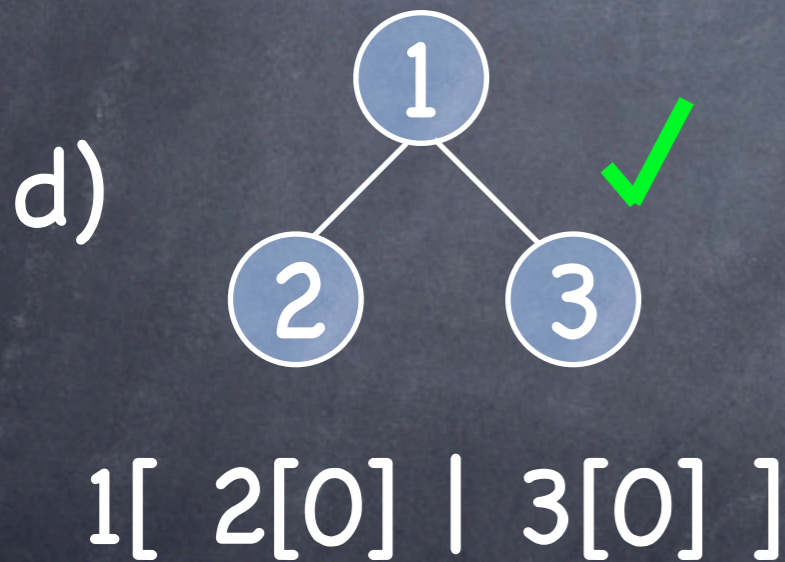
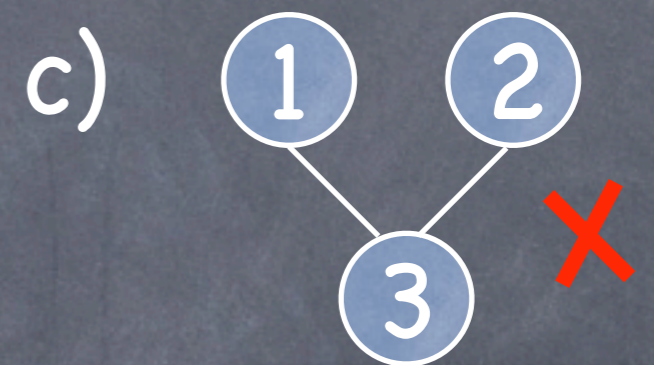
Tree Examples



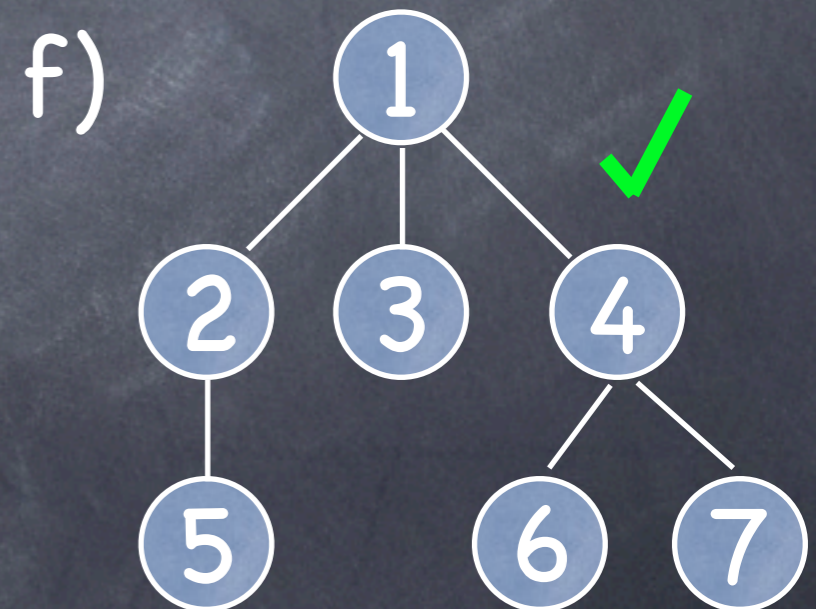
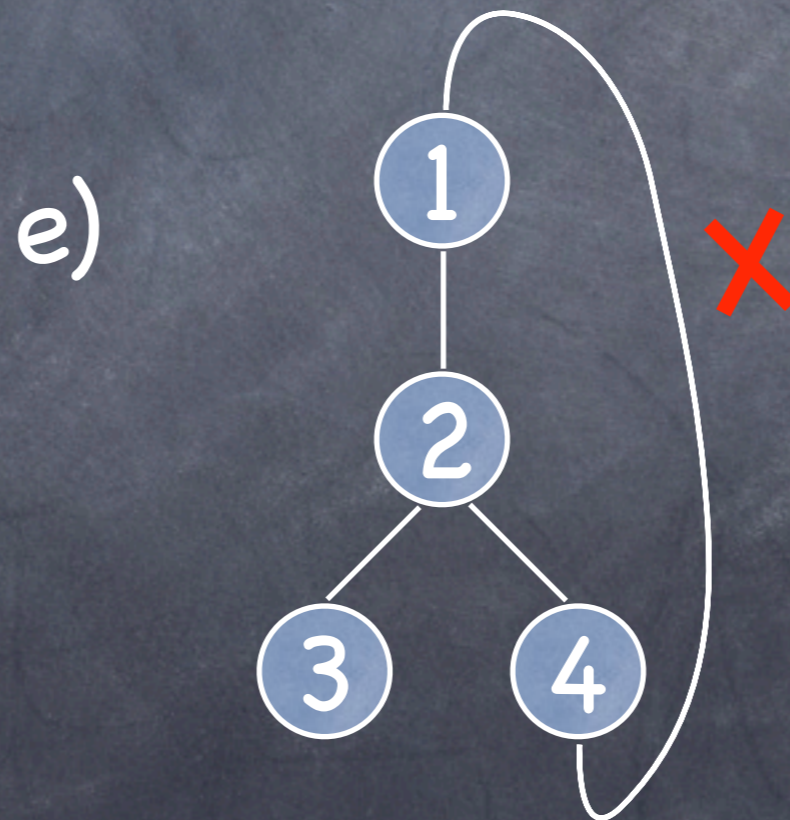
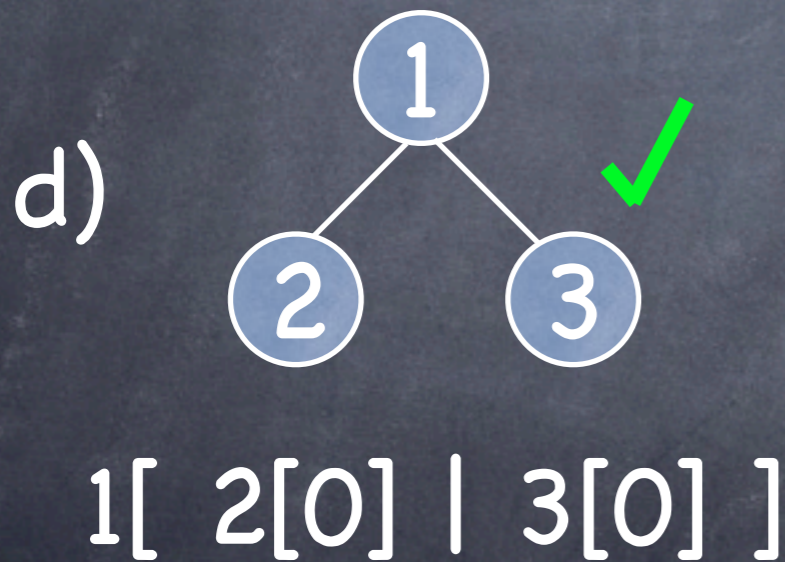
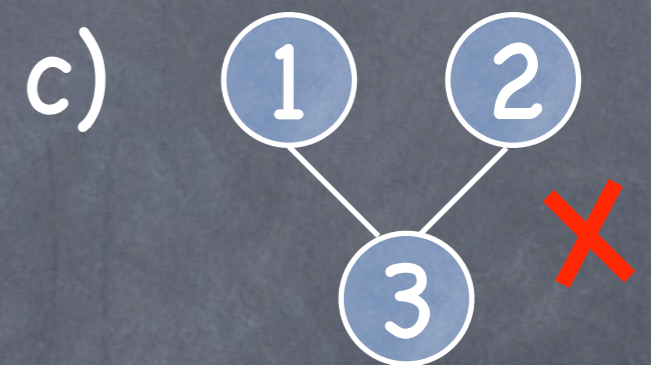
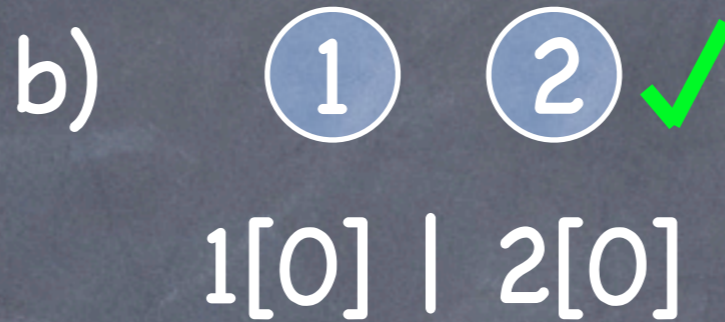
Tree Examples



Tree Examples



Tree Examples



$1[2[5[0]] \mid 3[0] \mid 4[6[0] \mid 7[0]]]$

Data Update

We want to describe the behavior of a program,

Eg:

```
{ colour(X, ?) }  
    paint(X, Green)  
{ colour(X, Green) }
```

Data Update

We want to describe the behavior of a program,

{ P } computer command { Q }

pre-condition

post-condition

Eg:

{ colour(X, ?) }

paint(X, Green)

{ colour(X, Green) }

Data Update

We want to describe the behavior of a program,

{ P } computer command { Q }

pre-condition

post-condition

pre-condition must hold before and post-condition must hold after, or we get a fault!

Eg:

{ colour(X, ?) }

paint(X, Green)

{ colour(X, Green) }

Local Data Update

{ $y=3$, $x=n$, $z=2$ }

addOne(x)

{ $y=3$, $x=n+1$, $z=2$ }

Local Data Update

{ $y=3$, $x=n$, $z=2$ }

addOne(x)

{ $y=3$, $x=n+1$, $z=2$ }



{ $x=n$ }

addOne(x)

{ $x=n+1$ }

Local Tree Update

$\{ m[t_1 \mid n[t_2] \mid t_3] \}$

$p := \text{goUpTree}(n)$

$\{ m[t_1 \mid n[t_2] \mid t_3] \wedge (p=m) \}$

$\{ n[t] \}$

$\text{deleteTree}(n)$

$\{ 0 \}$

$\{ n[t] \}$

$\text{addNodeAfter}(n,x)$

$\{ n[t] \mid x[0] \}$

Example – Family Trees

A more complex data structure,

Example – Family Trees

A more complex data structure,

database $D ::=$

Example – Family Trees

A more complex data structure,

database $D ::= 0_D$ empty database

Example – Family Trees

A more complex data structure,

database $D ::=$ O_D empty database
familyName[F] one family

Example – Family Trees

A more complex data structure,

database	$D ::=$	0_D	empty database
		familyName[F]	one family
		$D + D$	database join

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family tree $F ::=$	O_F	empty tree
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Example – Family Trees

A more complex data structure,

database $D ::=$	O_D	empty database
	familyName [F]	one family
	$D + D$	database join

family tree $F ::=$	O_F	empty tree
	name:marTo Gen:Age [F]	tree node

Example – Family Trees

A more complex data structure,

database $D ::=$	O_D	empty database
	familyName [F]	one family
	$D + D$	database join

family tree $F ::=$	O_F	empty tree
	name:marTo [F]	tree node
	Gen:Age	
	$F F$	ordered trees

Example - Family Tree

Nodes

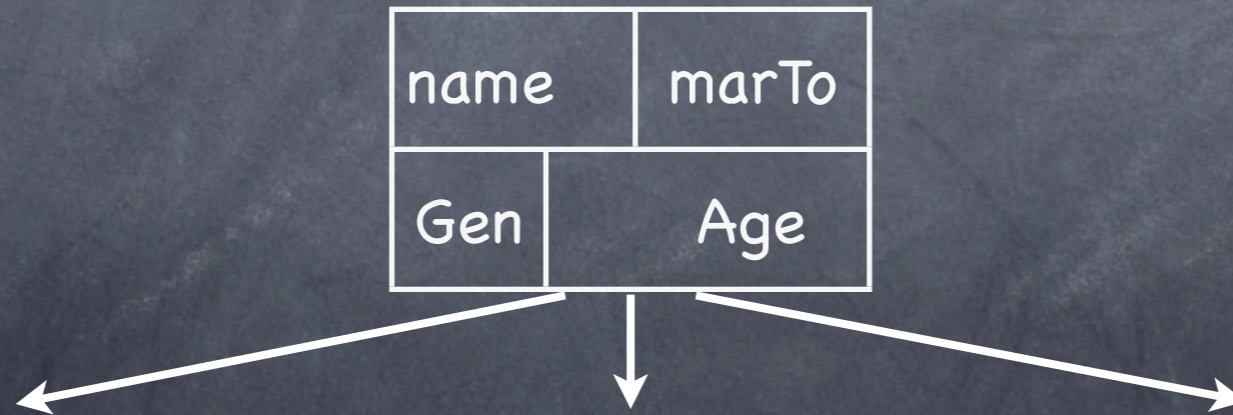
name:marTo [F] tree node
Gen:Age

Example - Family Tree

Nodes

name:marTo [F] tree node
Gen:Age

||



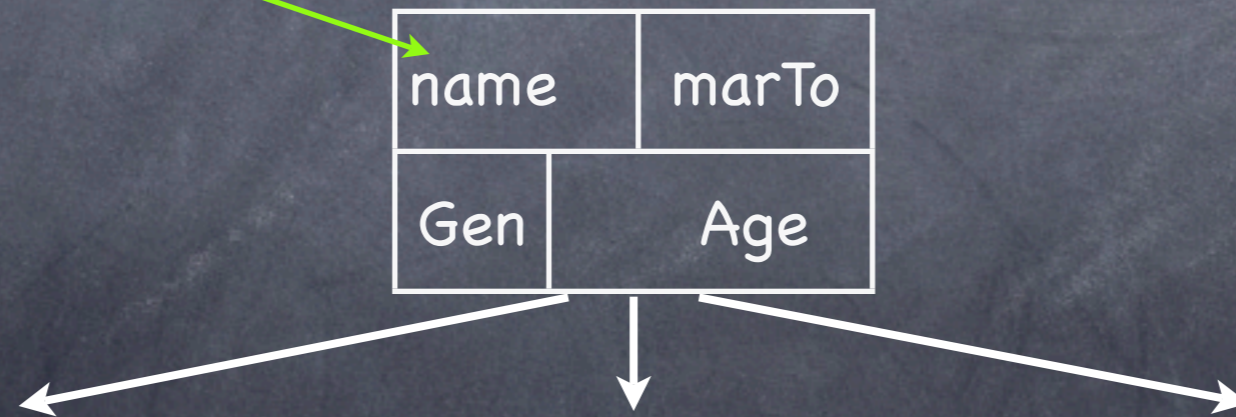
Example - Family Tree

Nodes

name:marTo [F] tree node
Gen:Age

person's name

||



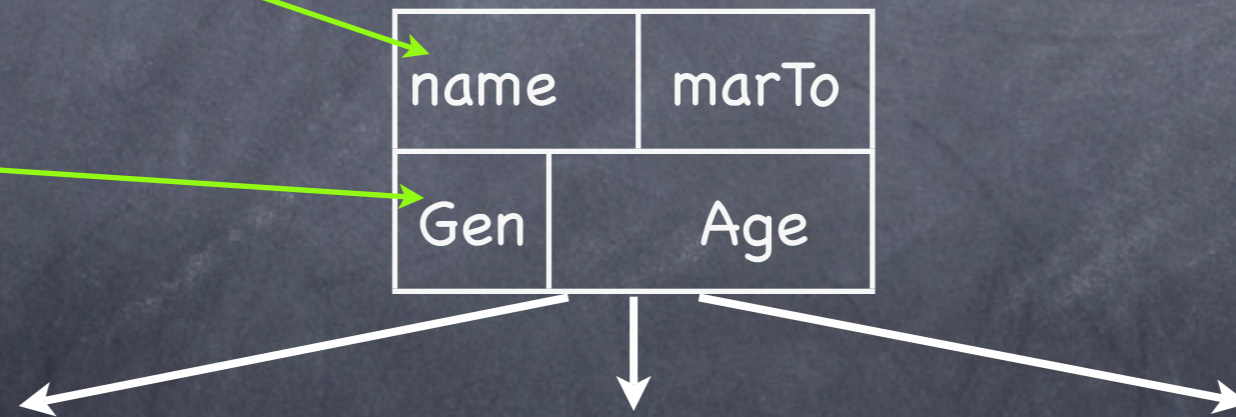
Example - Family Tree Nodes

name:marTo [F] tree node
Gen:Age

person's name

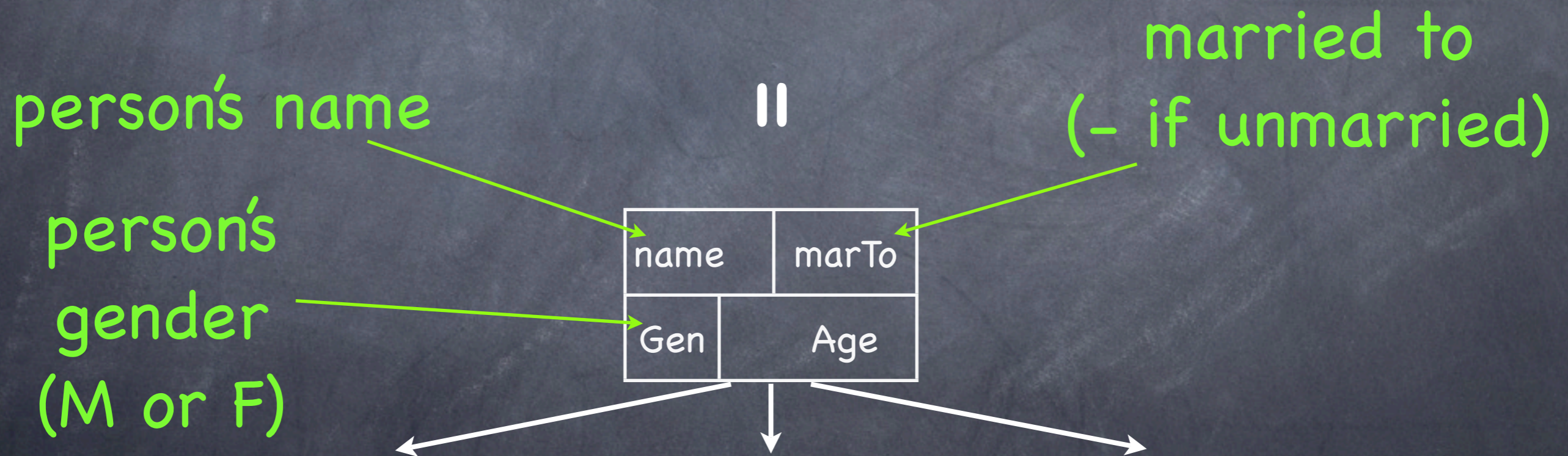
||

person's
gender
(M or F)



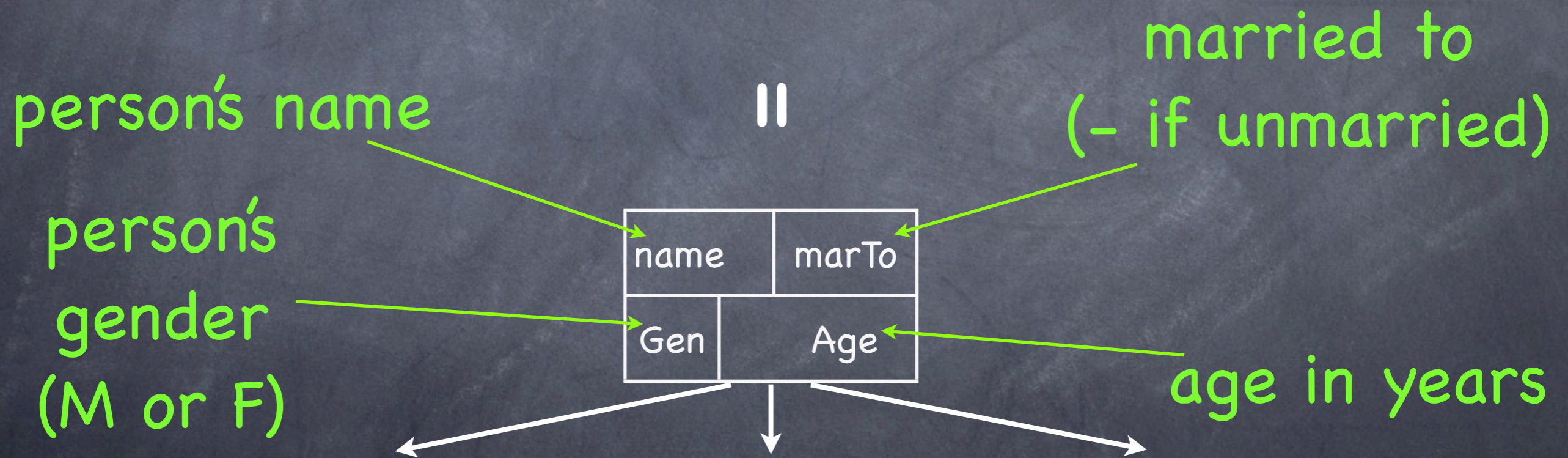
Example - Family Tree Nodes

name:marTo [F] tree node
Gen:Age



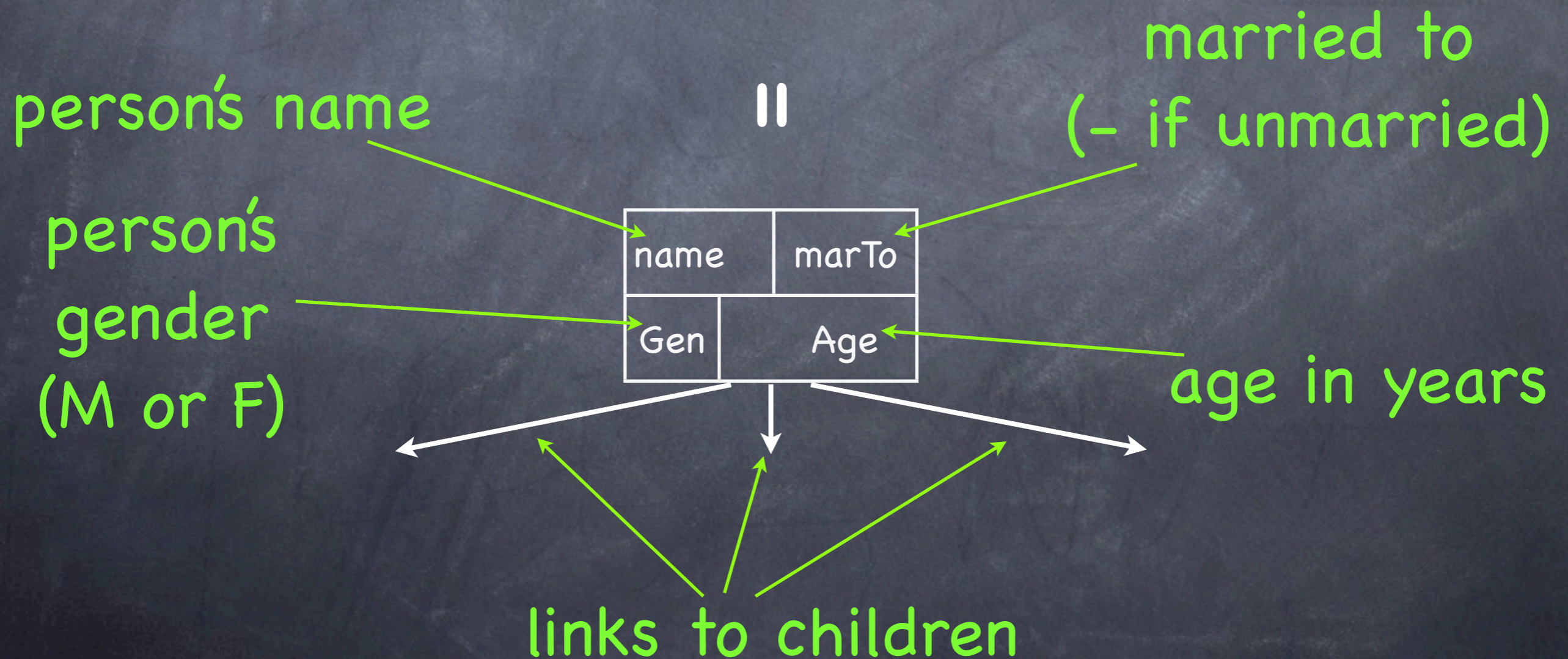
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name:marTo [F] tree node
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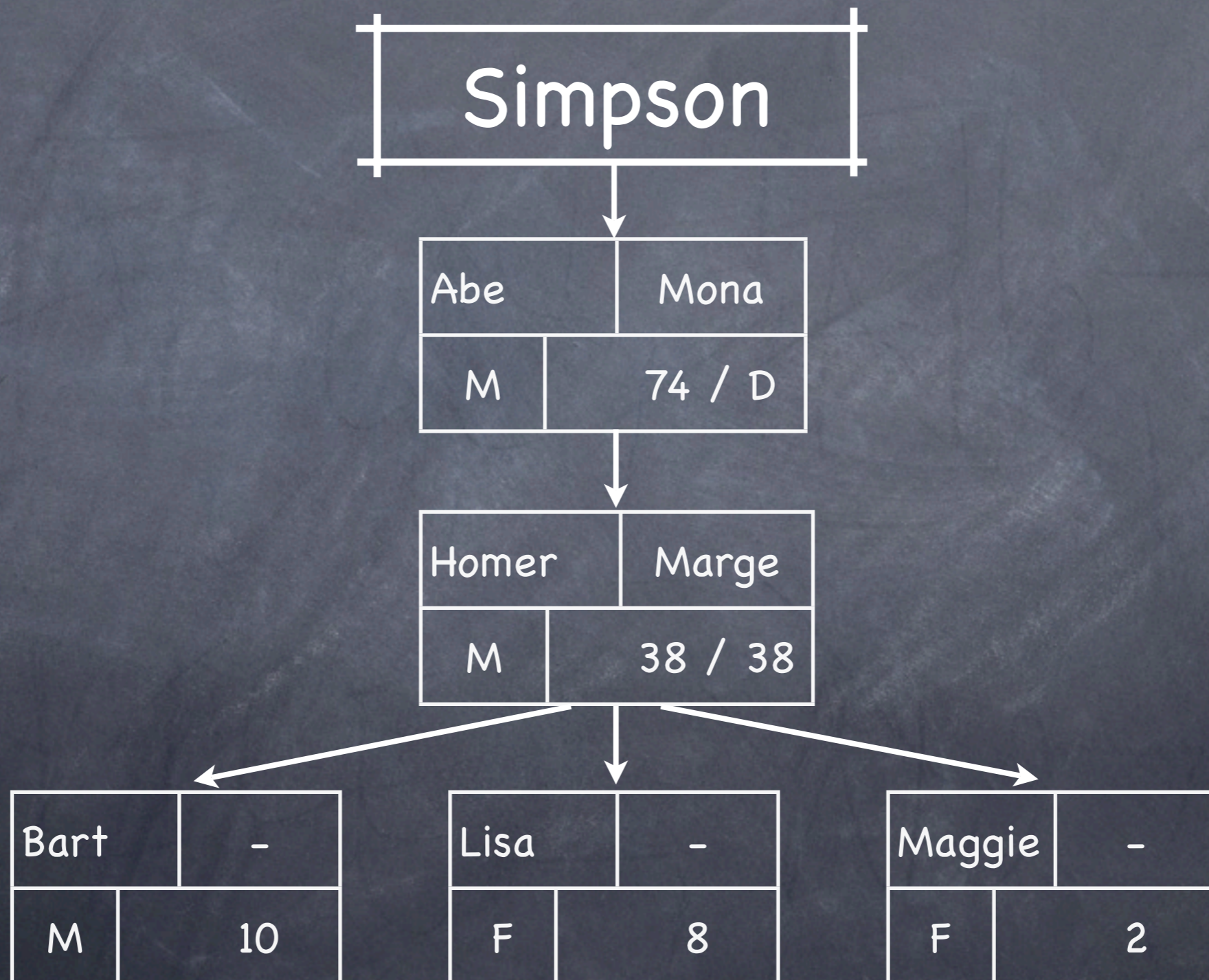


Example - Family Tree Nodes

name:marTo [F] tree node
Gen:Age



Example - The Simpsons



Example – Commands

Example - Commands

{

name	?
?	?

 } reName(name, nom) {

nom	?
?	?

 }

Example - Commands

{

name	?
?	?

 } reName(name, nom) {

nom	?
?	?

 }

{

name	?
?	?

 } reage(name, x) {

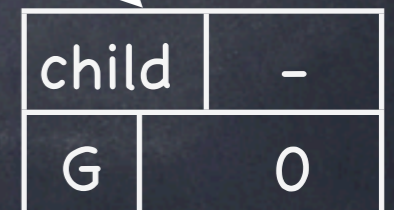
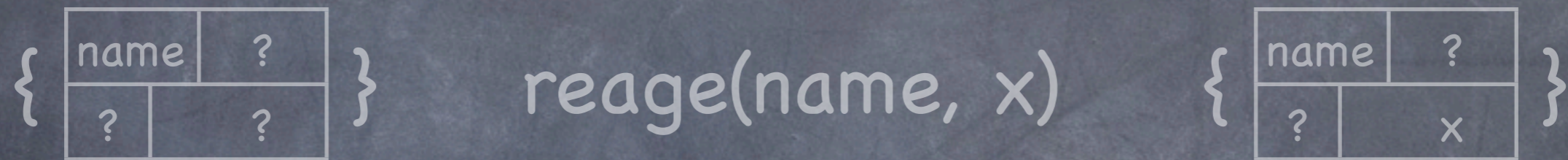
name	?
?	x

 }

Example - Commands



Example - Commands



Now you are going to
perform concurrent local
reasoning!

Example - Commands

